

# Lecture 16

## GPU Architectures

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# Key Performance Factors

- Parallelism
  - Amount data and computation processed at a time
- Clock frequency
  - Processing speed
- Memory bandwidth
  - Amount of data transferred at a time
- Memory latency
  - Time for each data element to be transferred
- Different applications are sensitive to different performance factors
- Different architectures address these factors in different ways



# CPUs with regards to the Performance Factors

- Parallelism
  - CPUs have multiple cores, where each has ILP
- Clock frequency
  - CPUs maximize clock frequency
  - But, power wall
- Memory bandwidth
  - DDR memory has limited bandwidth
- Memory latency
  - DDR memory has long latency
  - CPUs strive to hide the latency through:
    - On-chip caches to stage data
    - Out-of-order execution
    - Simultaneous multithreading



# Accelerators

- Graphics Processing Units (GPUs) have evolved for the gaming market
  - A GPU has many number-crunching cores
  - GPU vendors, such as NVIDIA and AMD, have tailored existing GPU architectures to the HPC market
    - Software ecosystem is important
- GPUs now firmly established in HPC industry



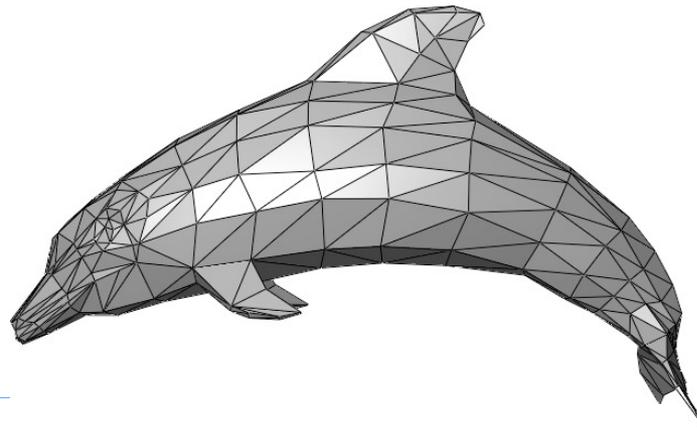
# GPUs with regards to the Performance Factors

- Parallelism
  - GPUs dedicate much more space to compute at the expense of caches, controllers, etc.
  - Much higher extent of parallelism than CPUs (many simple cores)
- Clock frequency
  - GPUs typically have lower clock-frequency than CPUs
  - But, GPUs achieve high performance through parallelism
- Memory bandwidth
  - GPUs use high bandwidth memory
  - GDDR or HBM2 stacked memory
- Memory latency
  - Similar to DDR
  - GPUs hide latency through hardware multithreading



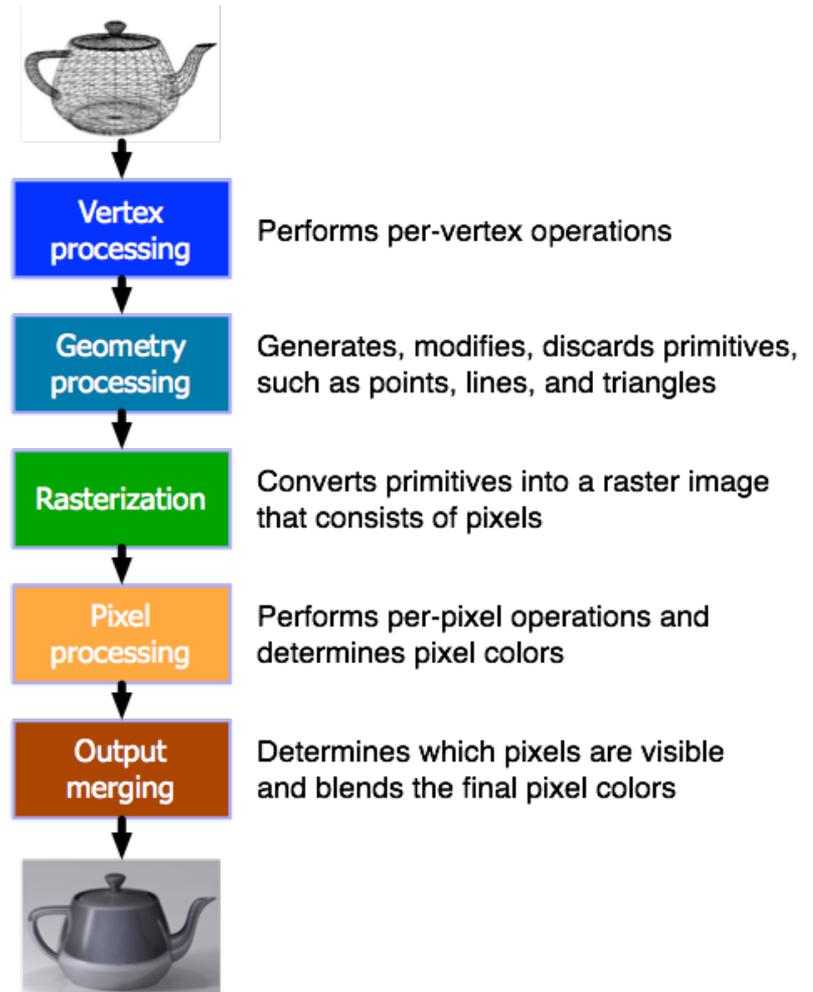
# Rendering

- The process of generating an image from a 3D model
- 3D modeling
  - The process of developing a mathematical representation (i.e., model) of any three-dimensional surface of an object
  - Polygon or triangle meshes



# Rendering (Graphics) Pipeline

- Generates 2D images from 3D models
- Supported by commodity hardware
- Some stages are programmable
  - Vertex
  - Geometry
  - Pixel
  - ...

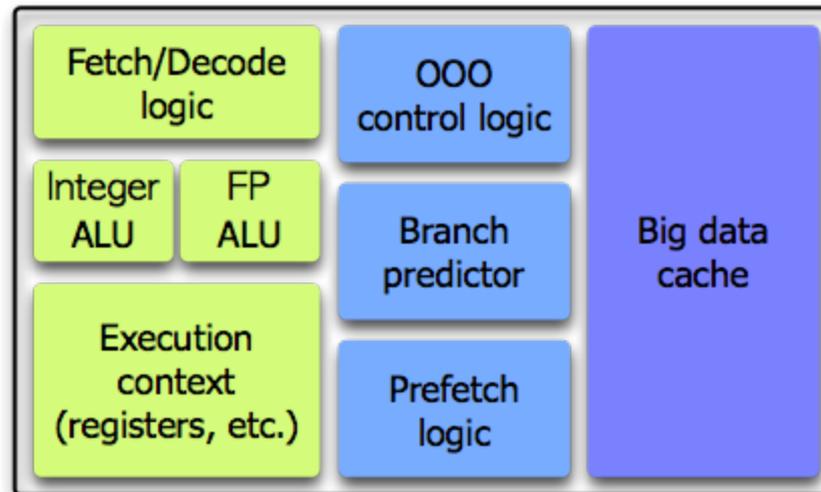


# Shaders

- Computer program that runs on the GPU and its purpose is to execute one of the programmable stages of the rendering pipeline

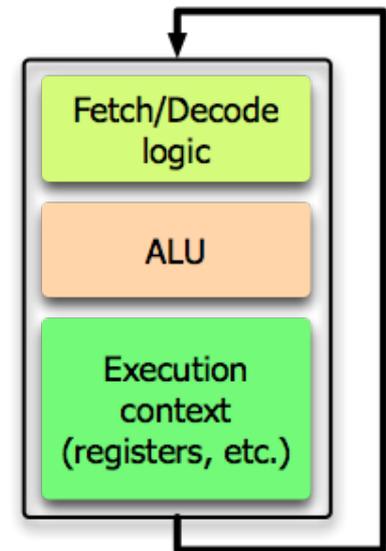


# General-purpose CPU



# Shader Cores

- Very simple, programmable
- No architecture components that make a single instruction stream run fast
- Logical graphics pipeline
  - Vertex shader, Geometry shader, Pixel shader, etc.
  - Graphics pipeline stages are implemented by visiting the programmable shader core several times



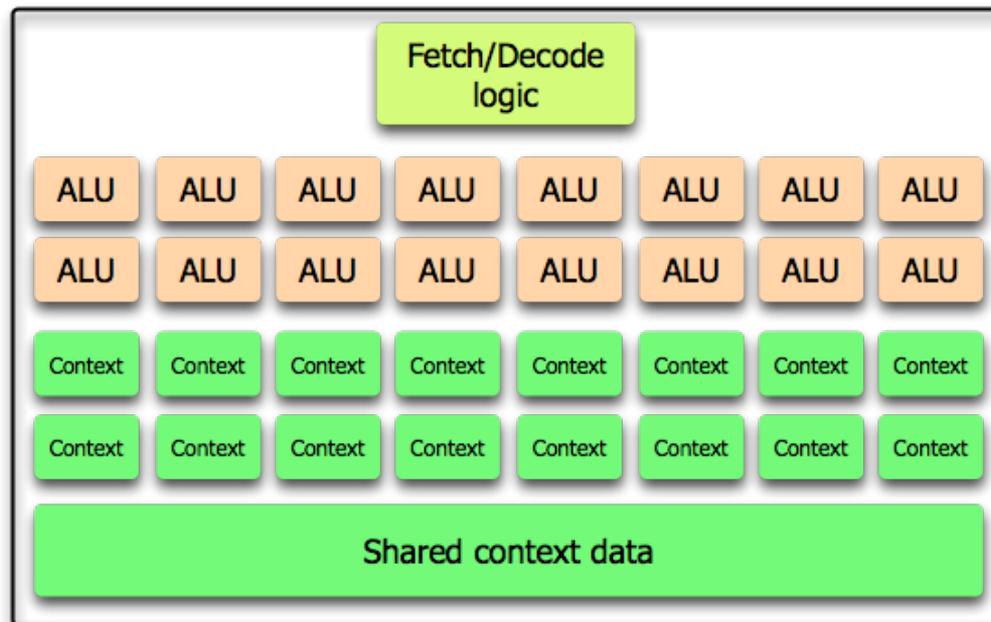
# Characteristics of GPU Applications

- Data independence between triangles and pixels
- Millions of triangles and pixels
- Can perform massively parallel processing



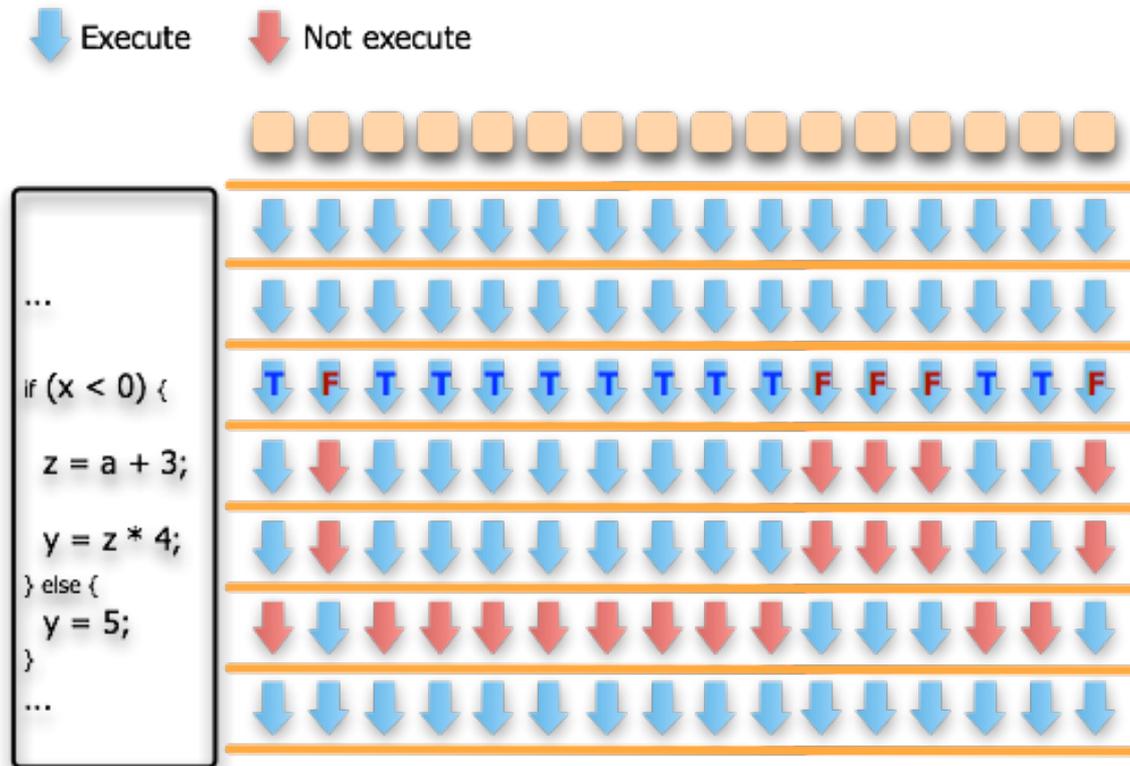
# Exploiting Massive Parallelism

- Streaming multiprocessors
  - SIMD processing across many ALUs
  - A single program counter across multiple ALUs
- SIMT
  - Single Instruction, Multiple Thread



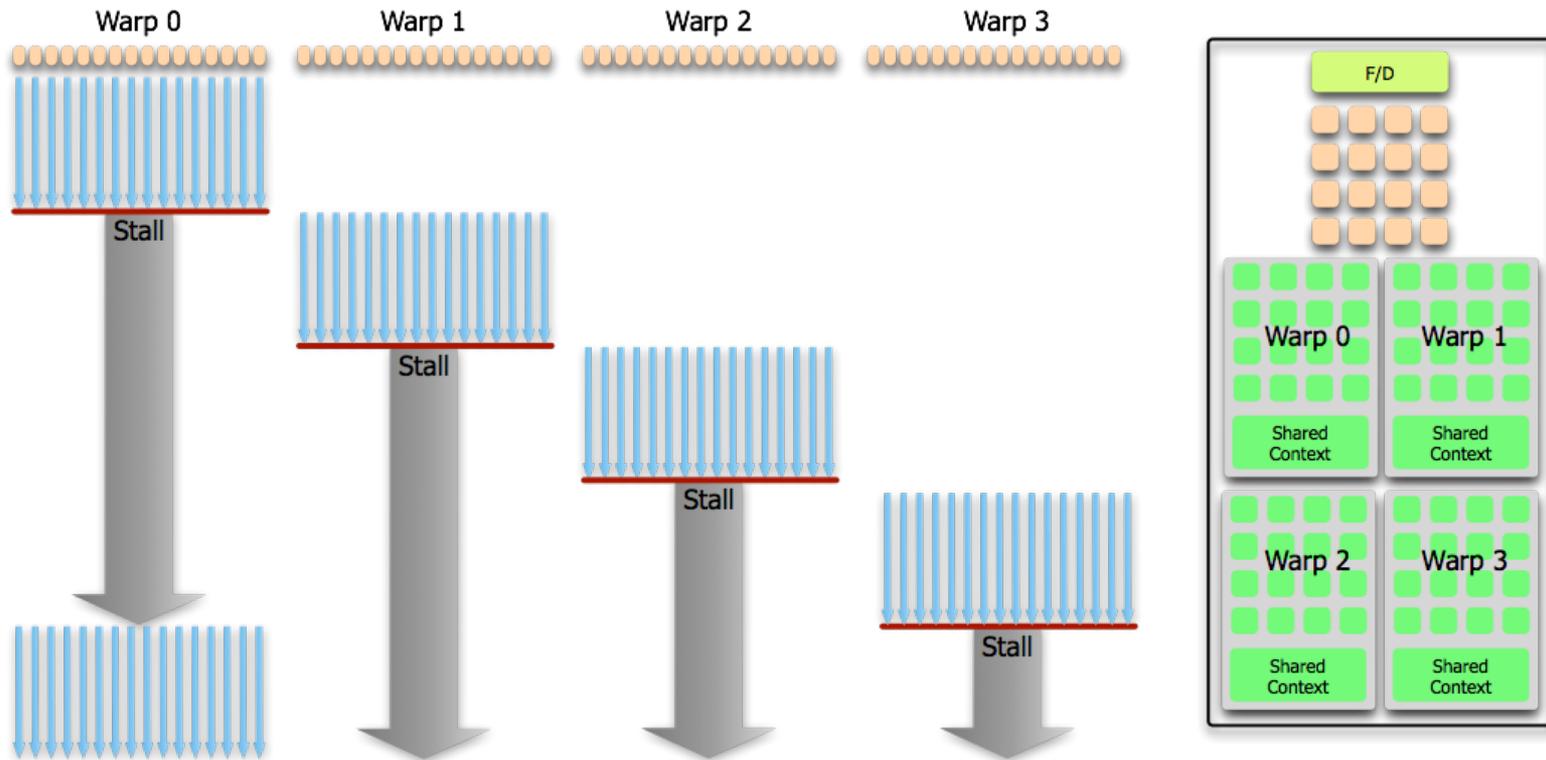
# Executing Branches

- Conditional execution in a warp
- Hardware automatically handles divergence



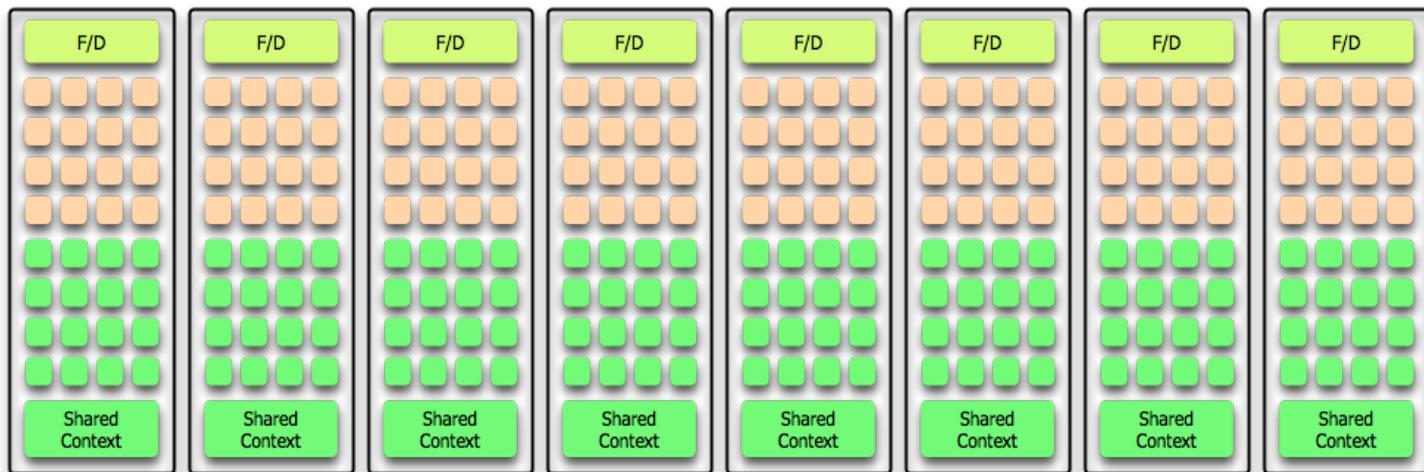
# Hardware Context Switch

- To avoid stalls caused by high latency operations
- A single SM can run more than one warp
  - A warp is a group of instruction execution instances and is the unit of context switch
  - All threads in a warp execute the same instruction at a time

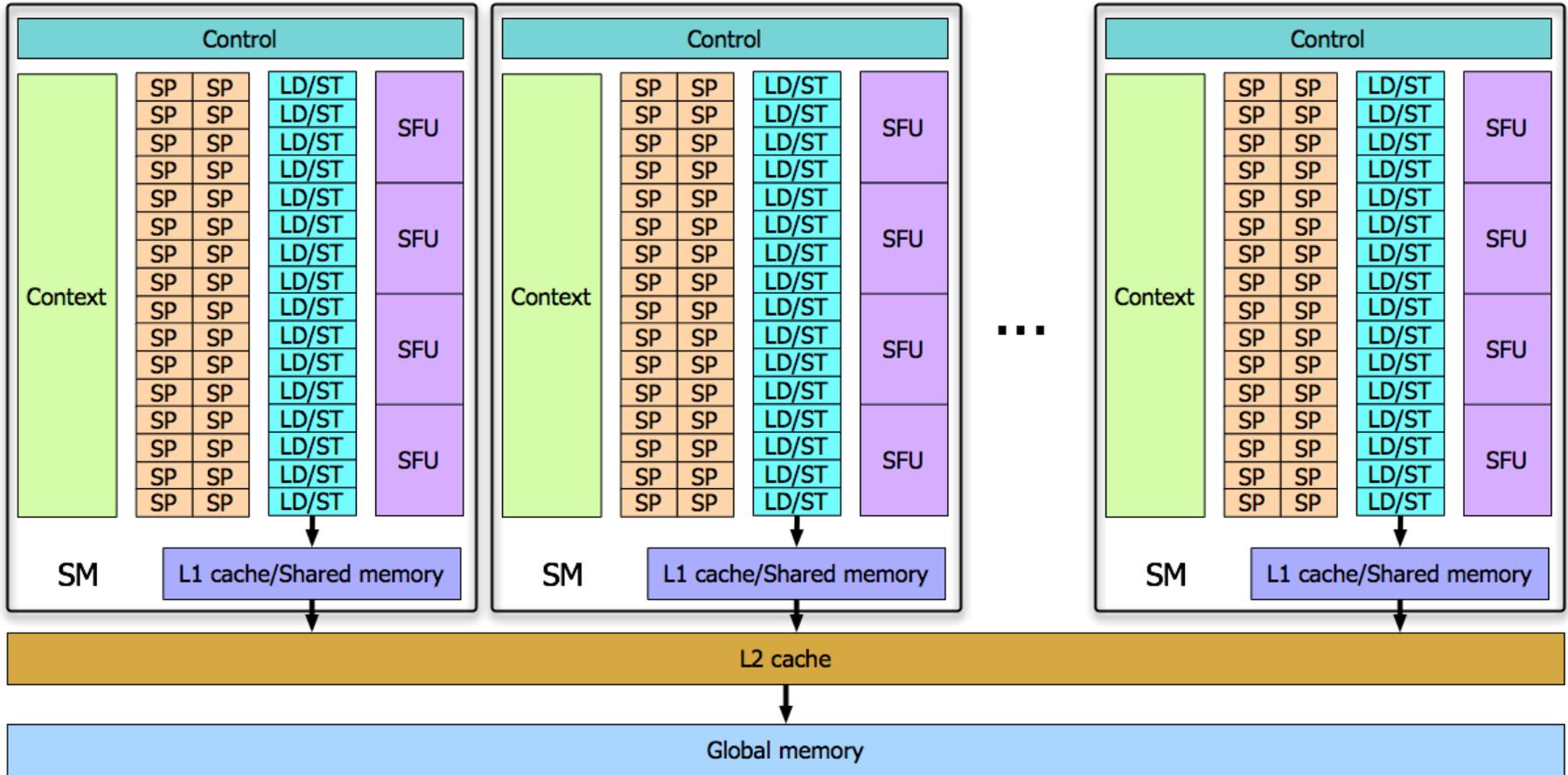


# Multiple Streaming Multiprocessors

- Different streaming multiprocessors (SMs) execute different shaders
- N SMs
  - N simultaneous instruction streams



# The Overall Picture



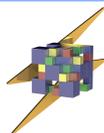
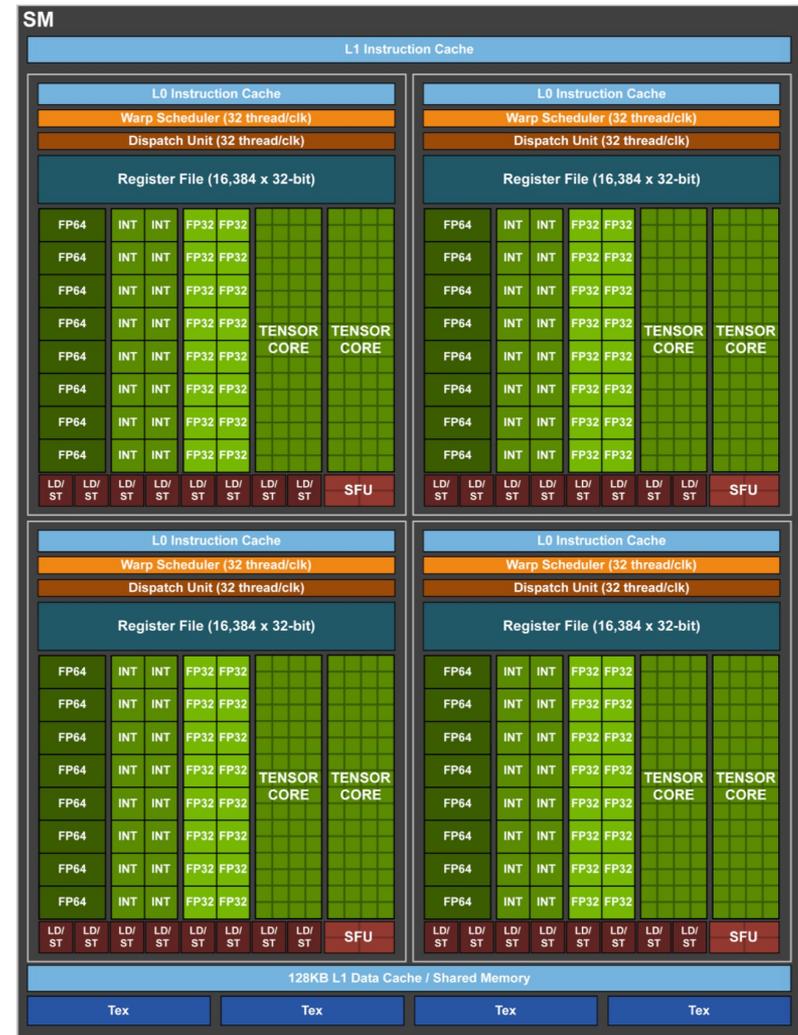
# GPU Summary

- Exploits massive data parallelism
  - Many simple compute units
  - SIMD (a single program counter)
  - Many threads and no synchronization between threads (for graphics applications)
- Hardware context switch
  - To tolerate high latencies



# Tensor Cores

- Tensor Cores give the Tesla V100 accelerator a peak throughput 12 times the 32-bit floating point throughput of the previous-generation Tesla P100
  - Enable AI programmers to use mixed precision to achieve higher throughput without sacrificing accuracy
- Tensor Cores are already supported for DL training in many DL frameworks including TensorFlow, PyTorch, MXNet, and Caffe2



# Tensor Cores (cont'd)

- Programmable matrix-multiply-and-accumulate units
- The Tesla V100 GPU contains 640 Tensor Cores: 8 per SM
- Each Tensor Core provides a  $4 \times 4 \times 4$  matrix processing array which performs the operation  $D = A \times B + C$ 
  - $A, B, C$  and  $D$  are  $4 \times 4$  matrices
  - Inputs  $A$  and  $B$  are FP16 matrices
  - The accumulation matrices  $C$  and  $D$  may be FP16 or FP32 matrices

$$\mathbf{D} = \begin{pmatrix} A_{0,0} & A_{0,1} & A_{0,2} & A_{0,3} \\ A_{1,0} & A_{1,1} & A_{1,2} & A_{1,3} \\ A_{2,0} & A_{2,1} & A_{2,2} & A_{2,3} \\ A_{3,0} & A_{3,1} & A_{3,2} & A_{3,3} \end{pmatrix} \begin{pmatrix} B_{0,0} & B_{0,1} & B_{0,2} & B_{0,3} \\ B_{1,0} & B_{1,1} & B_{1,2} & B_{1,3} \\ B_{2,0} & B_{2,1} & B_{2,2} & B_{2,3} \\ B_{3,0} & B_{3,1} & B_{3,2} & B_{3,3} \end{pmatrix} + \begin{pmatrix} C_{0,0} & C_{0,1} & C_{0,2} & C_{0,3} \\ C_{1,0} & C_{1,1} & C_{1,2} & C_{1,3} \\ C_{2,0} & C_{2,1} & C_{2,2} & C_{2,3} \\ C_{3,0} & C_{3,1} & C_{3,2} & C_{3,3} \end{pmatrix}$$

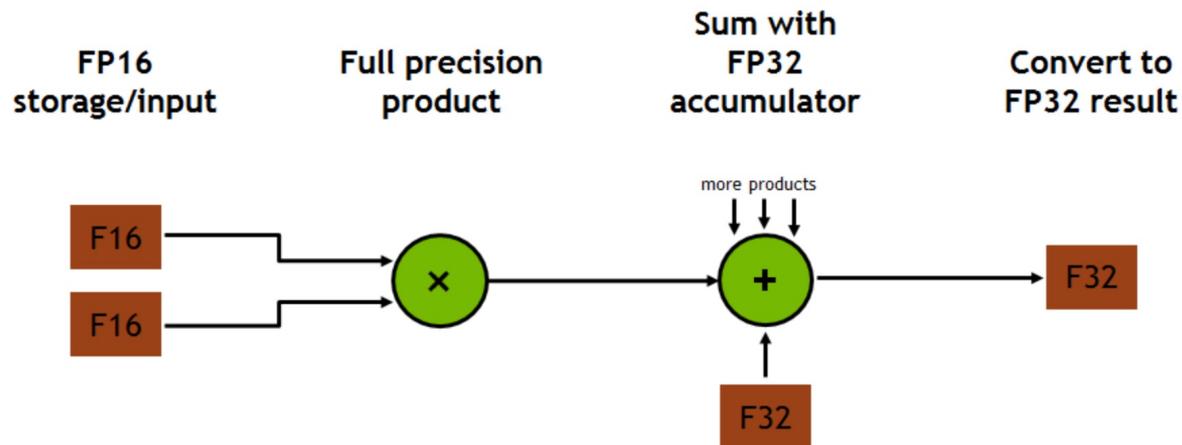
FP16 or FP32
FP16
FP16
FP16 or FP32

<https://developer.nvidia.com/blog/programming-tensor-cores-cuda-9/>



# Architecture

- Each Tensor Core performs 64 floating point FMA mixed-precision operations per clock
  - Tensor Cores operate on FP16 input data with FP32 accumulation
  - FP16 input multiply with full-precision product
  - FP32 accumulate



<https://developer.nvidia.com/blog/programming-tensor-cores-cuda-9/>



# Performance

- 8 Tensor Cores in an SM
  - A total of 1024 floating point operations per clock
    - Multiplication and addition
  - 8x increase in throughput for deep learning applications per SM compared to Pascal GP100 using standard FP32 operations
  - Total 12x increase in throughput for the Volta V100 GPU compared to the Pascal P100 GPU

	Tesla V100	RTX 2080*
Double precision peak performance	7 TFLOPS	300 GFLOPS
Single precision peak performance	14 TFLOPS	10 TFLOPS
Half precision peak performance using tensor core	112 TFLOPS	80 TFLOPS



# CUDA libraries for Tensor Cores

- cuBLAS and cuDNN
  - cuBLAS uses Tensor Cores to speed up GEMM computations
  - cuDNN uses Tensor Cores to speed up both CNNs and RNNs
- Intrinsic in CUDA programming model

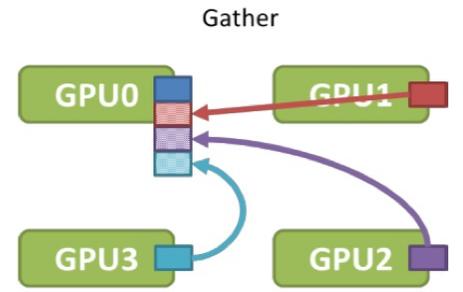
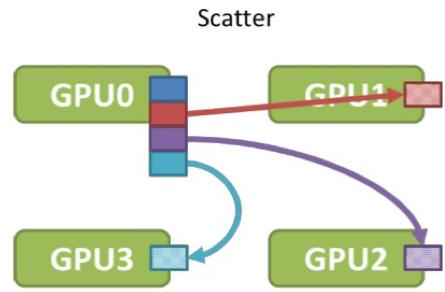
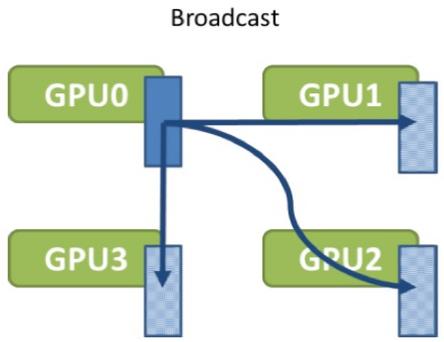


# NCCL

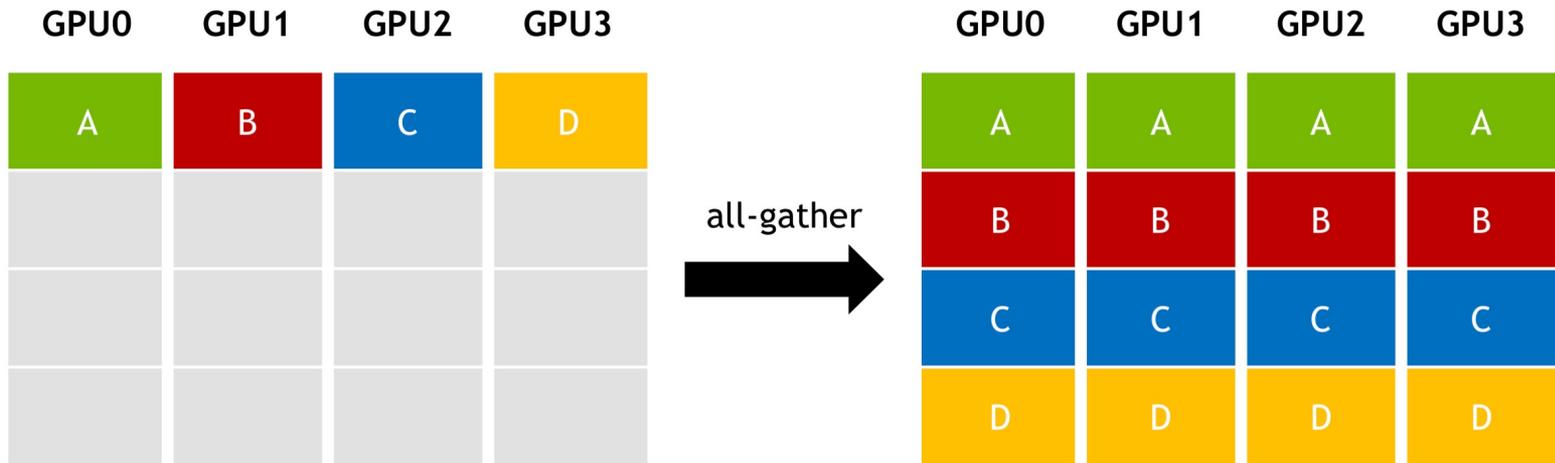
- NVIDIA Collective Communication Library
- Between GPUs in a node, or across nodes
- Similar to MPI collective communication API
  - Broadcast
  - Scatter
  - Gather
  - All-Gather
  - All-to-All
  - Reduce
  - All-Reduce



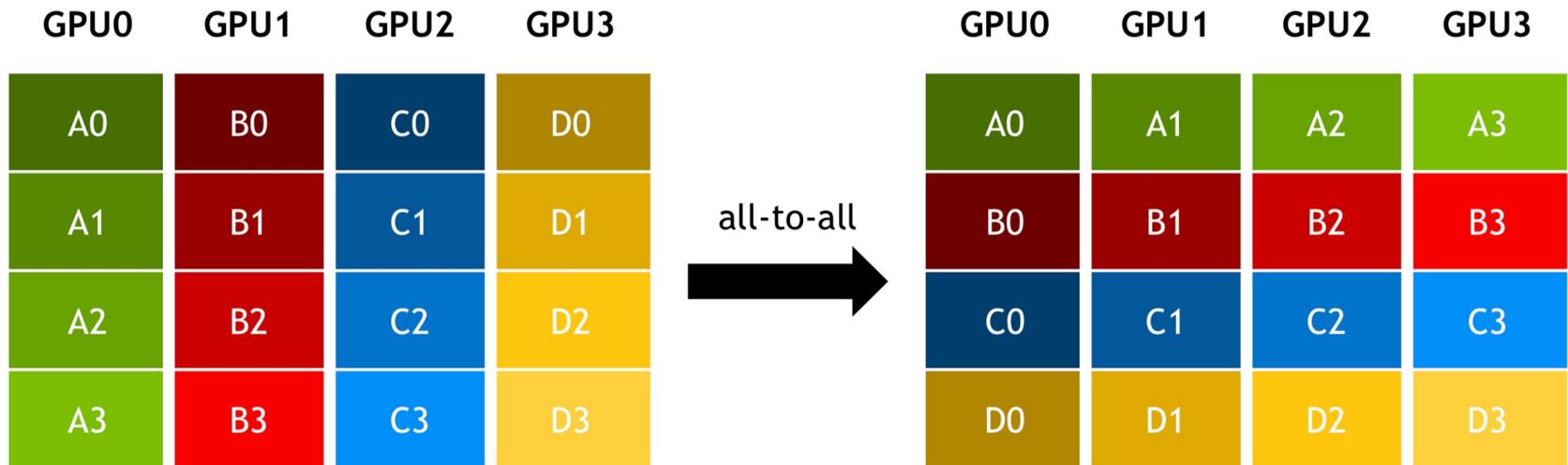
# Broadcast, Scatter, and Gather



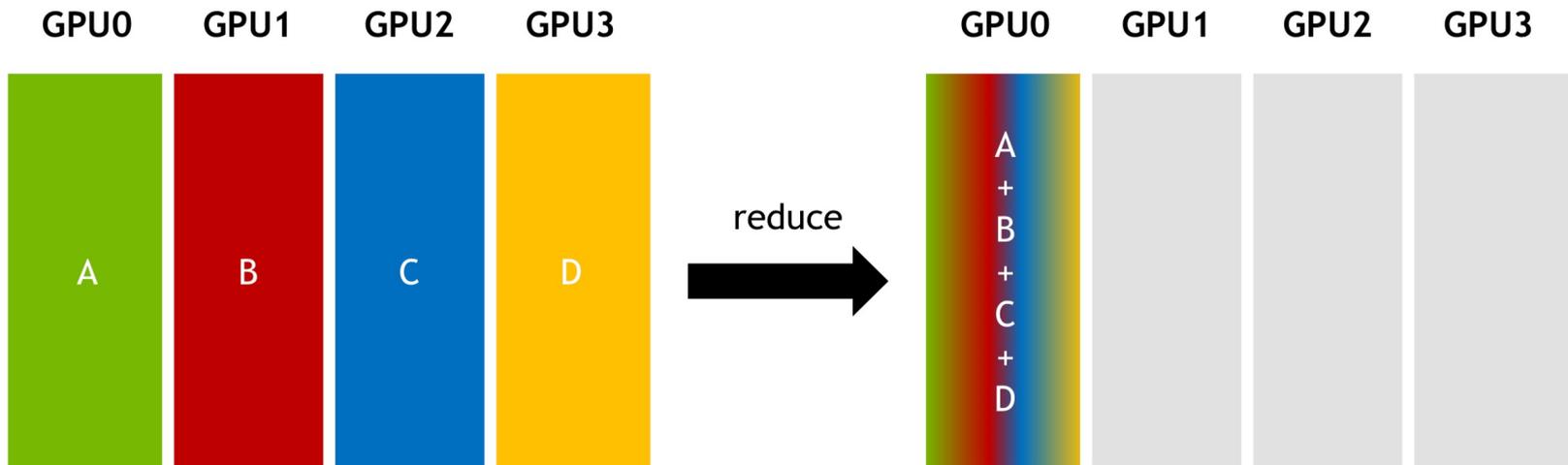
# All-Gather



# All-to-All



# Reduce



# All-Reduce

